REÁ 80-3000 Electric Actuator Manual
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CHECK POINTS BEFORE USING ACTUATOR

Mechanical
- Check external: Check if drive bushing, painting, handle and lever are OK or not.
- Compare specification: Compare if specification of the delivered actuator is suitable for your specification of application
- Check options: Check if all options are correct or not

Electrical
- Check if electrical specification is correct or not (Wiring diagram inside of actuator, name plate).
- Check if the electrical power is correct or not.

Other checking points
Check if instruction manual, test report (Warranty papers) and electrical wiring diagram are supplied or not.

INTRODUCTION OF REA ACTUATOR

Name of Main Parts
Externals

REA 80-1200
Internals

REA 80-1200

REA 2000-3000
### PERFORMANCE

<table>
<thead>
<tr>
<th>MODEL</th>
<th>Maximum Output Torque</th>
<th>Operating Time(s) 60Hz/50Hz</th>
<th>Maximum Bore Size</th>
<th>Motor Class F Power(W) 60Hz/50Hz</th>
<th>Nominal Current(A) 60/50Hz</th>
<th>Duty Cycle</th>
<th>Manuel Turn Number</th>
<th>Weight</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Nm</td>
<td>°</td>
<td>mm</td>
<td>1 Phase</td>
<td>3 Phase</td>
<td>110V</td>
<td>220V</td>
<td>380V</td>
</tr>
<tr>
<td>REA - 80</td>
<td>80</td>
<td>13/16</td>
<td>Ø20</td>
<td>106/103</td>
<td>NA</td>
<td>1,00/0,97</td>
<td>0,45/0,45</td>
<td>NA</td>
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<tr>
<td>REA - 150</td>
<td>150</td>
<td>21/25</td>
<td>Ø22</td>
<td>185/166</td>
<td>112/216</td>
<td>1,70/1,50</td>
<td>0,84/0,73</td>
<td>0,28/0,37</td>
</tr>
<tr>
<td>REA - 200</td>
<td>200</td>
<td>21/25</td>
<td>Ø22</td>
<td>185/166</td>
<td>112/216</td>
<td>1,70/1,50</td>
<td>0,84/0,73</td>
<td>0,28/0,38</td>
</tr>
<tr>
<td>REA - 300</td>
<td>300</td>
<td>26/31</td>
<td>Ø35</td>
<td>177/148</td>
<td>130/171</td>
<td>1,67/1,37</td>
<td>0,81/0,68</td>
<td>0,27/0,33</td>
</tr>
<tr>
<td>REA - 600</td>
<td>600</td>
<td>26/31</td>
<td>Ø35</td>
<td>390/410</td>
<td>184/236</td>
<td>3,56/4,27</td>
<td>1,30/1,40</td>
<td>0,42/0,51</td>
</tr>
<tr>
<td>REA - 800</td>
<td>800</td>
<td>31/37</td>
<td>Ø45</td>
<td>483/389</td>
<td>312/427</td>
<td>4,93/3,59</td>
<td>2,20/1,80</td>
<td>0,61/0,83</td>
</tr>
<tr>
<td>REA - 1200</td>
<td>1200</td>
<td>31/37</td>
<td>Ø45</td>
<td>483/389</td>
<td>312/427</td>
<td>4,93/3,59</td>
<td>2,20/1,80</td>
<td>0,61/0,84</td>
</tr>
<tr>
<td>REA - 2000</td>
<td>2000</td>
<td>93/112</td>
<td>Ø65</td>
<td>483/389</td>
<td>312/427</td>
<td>4,93/3,59</td>
<td>2,20/1,80</td>
<td>0,61/0,85</td>
</tr>
<tr>
<td>REA - 3000</td>
<td>3000</td>
<td>93/112</td>
<td>Ø65</td>
<td>483/389</td>
<td>312/427</td>
<td>4,93/3,59</td>
<td>2,20/1,80</td>
<td>0,61/0,85</td>
</tr>
</tbody>
</table>

### STANDARD SPECIFICATION

<table>
<thead>
<tr>
<th>Feature</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Enclosure</td>
<td>Weatherproof enclosure IP67, NEMA 4 and 6</td>
</tr>
<tr>
<td>Power supply</td>
<td>110 / 220V AC 1PH, 380 / 440V AC 3PH 50 / 60Hz, 10%</td>
</tr>
<tr>
<td>Control power supply</td>
<td>110 / 220V AC 1PH, 50 / 60Hz, 10%</td>
</tr>
<tr>
<td>Duty cycle(on-off)</td>
<td>S2, 100% Max 30Min</td>
</tr>
<tr>
<td>Duty cycle(modulating)</td>
<td>S4, 70% Max 300~1600 start/hour</td>
</tr>
<tr>
<td>Motor</td>
<td>Induction motor (Reversible motor)</td>
</tr>
<tr>
<td>Limit switches</td>
<td>Open / close, SPDT, 250V AC 16A rating</td>
</tr>
<tr>
<td>Additional limit switches</td>
<td>Open / close, SPDT, 250V AC 16A rating (except REA80-100)</td>
</tr>
<tr>
<td>Torque switches</td>
<td>Open / close, SPDT, 250V AC 16A rating (except REA80-100)</td>
</tr>
<tr>
<td>Stall protection/operating temp</td>
<td>Built-in thermal protection, open 150°C ± 5°C/ close 97°C± 15°C</td>
</tr>
<tr>
<td>Travel angle</td>
<td>90°±10°(0~110°)</td>
</tr>
<tr>
<td>Indicator</td>
<td>Continuous position indicator</td>
</tr>
<tr>
<td>Manual override</td>
<td>Declutching mechanism</td>
</tr>
<tr>
<td>Self locking</td>
<td>Provided by double worm gearing</td>
</tr>
<tr>
<td>Mechanical stopper</td>
<td>2 external adjustable screws</td>
</tr>
<tr>
<td>Space heater</td>
<td>10W(110/220V AC) Anti-condensation</td>
</tr>
<tr>
<td>Cable entries</td>
<td>Three PF3/4 tap (standard type only)</td>
</tr>
<tr>
<td>Lubrication</td>
<td>Grease moly (EP type)</td>
</tr>
<tr>
<td>Terminal block</td>
<td>Spring loaded lever push type</td>
</tr>
<tr>
<td>Materials</td>
<td>Steel, Aluminium alloy, Al bronze, Polycarbonate</td>
</tr>
<tr>
<td>Ambient temperature</td>
<td>-20 ~+70 (except option electronic board)</td>
</tr>
<tr>
<td>Ambient humidity</td>
<td>90% RH Max.(non-condensing)</td>
</tr>
<tr>
<td>Anti vibration</td>
<td>X Y Z 10g, 0.2~34Hz, 30minute</td>
</tr>
<tr>
<td>External coating</td>
<td>Anodizing treatment before dry powder, Polyester</td>
</tr>
</tbody>
</table>
### OPTIONAL SPECIFICATION

<table>
<thead>
<tr>
<th>EXA</th>
<th>Explosion proof enclosure actuator (Exed II B T4)</th>
<th>REA-series</th>
</tr>
</thead>
<tbody>
<tr>
<td>WTA</td>
<td>Watertight enclosure actuator (IP68 10M 72HR)</td>
<td>REA-series</td>
</tr>
<tr>
<td>PIU</td>
<td>Potentiometer unit (0~1)</td>
<td>REA-series</td>
</tr>
<tr>
<td>PCU</td>
<td>Proportional control unit (input, output 0<del>10V DC, 4</del>20mA DC)</td>
<td>REA-series</td>
</tr>
<tr>
<td>ATS</td>
<td>Additional torque switches (SPDT x 2EA 250V AC 10A Rating) except REA-80/100</td>
<td></td>
</tr>
<tr>
<td>LCU-B</td>
<td>Integral control (LCU + IMS + phase protect indicator) except REA-80/100</td>
<td></td>
</tr>
<tr>
<td>LCU-C</td>
<td>Digital display control (LCU + IMS + auto phase discriminator) except REA-80/100</td>
<td></td>
</tr>
<tr>
<td>CPT</td>
<td>Current position transmitter (output 4~20mA DC)</td>
<td>REA-series</td>
</tr>
<tr>
<td>RBP</td>
<td>Rechargeable battery backup</td>
<td>REA-80/100, 150, 300</td>
</tr>
<tr>
<td>DCM</td>
<td>DC motor (24V DC)</td>
<td>REA-80/100, 150, 300</td>
</tr>
<tr>
<td>ADCM</td>
<td>Multi AC/DC 24V(integral)</td>
<td>REA-80/100, 150, 300</td>
</tr>
<tr>
<td>LPA</td>
<td>Lever plate actuator</td>
<td>except REA-80/100</td>
</tr>
<tr>
<td>SLU</td>
<td>Signal lamp unit (white-power on, red-open, green-close, yellow-over torque) except REA-80/100</td>
<td></td>
</tr>
<tr>
<td>FPA1</td>
<td>Fire Proofing Actuator 1050± 5 °C/ 50min</td>
<td>Engineering consult in advance</td>
</tr>
<tr>
<td>FPA2</td>
<td>Fire Proofing Actuator 250± 5 °C/ 150min</td>
<td>Engineering consult in advance</td>
</tr>
</tbody>
</table>

### SPECIFICATION

**Features and structure**

**General:**
REA series actuator is designed for the 90 degree turn application such as damper, ball, plug, butterfly valve and other equipment.

**Range of torque**
Min. 80Nm to Max 3000Nm. In between there are 9 models and cater for various torque depending on application. Models are REA-80, 150, 200, 300, 500, 800, 1200, 2000 and 3000.

Applicable size of valve
- Butterfly valve: 50mm (2") ~ 600mm (24")
- Ball valve: 40mm (1 1/2") ~ 350mm (16")

**Body**
Material is hard-anodized AL alloy and external coating of epoxy powder is suitable for the severe condition especially against the corrosion. Housing is designed in accordance with standard of ex-proof and IP68.

**Sealing**
Sealing carried out by the O-rings guarantees IP68.(10m under water 10days)

**Manual Override**
Just by pulling over the lever, operating mode is switched to manual. And just supplying electrical power to actuator, clutch is automatically disengaged from manual and operating mode is switched to electric operation.
**Gear & Self locking**
2nd staged Double worm gearing prevents movement caused by back force transfer red from valve and it provides the exact and stable position of actuator and valve when electrical power is off. High efficiency, low noise level and trouble free design are another advantage.

**Manual hand wheel**
The Size of hand wheel is designed according to required torque to move the actuator, so that operator can easily move the actuator by hand.

**Motor**
Motor specially designed for REA actuator has several features such as high output power, high efficiency and thermostat installed inside of motor prevent overheat of motor and thermal damage of motor coil.

**Limit switch**
Since limit switch is directly driven by the 2nd output shaft, position during operation is continuous and accurate. Setting of Cam is so easy and once cam setting is done, position is almost permanent unless operator changes setting again.

**Torque switch**
Torque switch driven by the 2nd output drive shaft for continuous and accurate torque detection. Torque spring which detects the variation of torque during operation is installed for preventing damage of valve and actuator under overload condition. Once actuator is under overload, torque switch is tripped and actuator stops immediately. Switches are installed for both open and close direction. This switches set by factory can not be set again without check with factory.

**Space heater**
Space heater is installed for preventing damage caused by condensed water inside of actuator and includes thermostat inside to prevent overheating. Temperature of heater can be set as per environmental condition.

**Stopper bolt**
Stopper bolt installed both close and open direction prevents actuator’s travel over the limit during manual operation and also protects internal gearing from its breakaway.

**Indicator**
Indicator directly driven by 2nd output drive shaft has 4 signal LEDs to show the current operating situation of actuator (Open/Close/Over torque/Power ON-Off). Operator perceives exact current operating situation even from a distance.

**Terminal block**
Spring loaded terminal strip is very strong against vibration and to add the number of strip for additional connection is so simple.

**Wiring**
Basic wiring is standardized to be simplest and optimal, so that variation depending on electrical specification and options can be so easy and simple.

**Adaption**
Mounting base is designed according to ISO5211 but different dimension depending on application is also possible. Removable drive bushing provides convenient machining for adaption.
Lubrication
Using Greas Moly EP type, no need to refill lubricant for the long time.

Others
REA guaranty high performance, high quality product throughout various and severe test and inspection.

MOUNTING BASE

Mounting base (ISO5211)

REA 80

REA 150-200

REA 300-600

REA 800-1200

REA 200-3000
ACTUATOR DRIVE BUSHING

REA 80

REA 800-1200

REA 150-200

REA 200-3000

REA 300-600

REA 200

REA 350 (MAX)

REA 450 (MAX)

REA 650 (MAX)
SETTING

Manual operation
a Pull over the lever toward hand wheel until lever stands perpendicularly.
b If lever does not stand perpendicularly, pull over it again turning hand wheel slowly.
c There is casting mark to indicate rotating direction on hand wheel.
d Clockwise is close direction and counter clockwise is open direction.
e No need to position the lever to original for electrical operation.
f Once electrical power is on, the lever automatically return its original position by internal clutch mechanism.

Limit switch setting
a Pull over the lever for manual operation and turn hand wheel to move actuator full close (or open) position.
b Loose the bolts tightening cam by L- wrench, and turn CLS (or OLS) cam to CW (or to CCW), so that cam may hit the lever of close (or open) limit switch. Then tighten the bolt by L- wrench.

torque switches
Torque Switches are set by factory before delivery and therefore no need to set the switches again, but just do as follows for check if switches functions well.
a Push the lever of close switches by screw driver until it sounds "click" then actuator should stop immediately. If it stops, switches work well.
b Check open switches as per just same with above.
• No guaranty in performance once these switches are set again.
• Before setting, if it is compulsory, please consult with factory.

Stopper bolt setting
a Before manual operation, get both nuts loose which are engaged with stopper bolts and turn stopper bolt to come out by 3 ~ 4 threads.
b Move actuator full close position by manual. Once cam hit the lever of limit switch to trip, stop manual operation.
c Then turn close stopper bolt to go forward until it does not go further (end of stopper bolt contacts the 2nd worm wheel).
d Turn close stopper bolt to come out by 2 threads and tighten the loosen nut.
e Do as per same with above for open stopper bolt.
Indicator setting

a. Move actuator full close position and turn indicator by hand until orientation of indicator is aligned to the figure of window.

b. Tighten the bolt (Be careful not to be injured by the cutting edge of indicator and leakage of electricity when power is on)

c. Figure of Window and indicator

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[Diagrams of REA 80, REA 150-1200, REA 2000-3000]
RECOMMENDATION FOR INSTALLATION OF ACTUATOR IN THE PIPELINE

Location of actuator on the pipeline

- No limit, but it is recommended to install actuator in the position which cable entry face the ground orientation for water tight function and hand wheel faces front for easy manual operation without interruption.
- Reserve the space for maintenance.

Orientation of installation of actuator
ELECTRICAL WIRING

Cable and conduit

Cable entries are machined with PF3/4” tap and sealed by Plug before delivery.

- Please remain the plug as it is if user doesn’t use both cable entries.
- Please make sure to seal the entries by using rubber or metallic packing after wiring, so that water may not come in.
- When user use actuator as ex-proof, please make sure to use the certified connection component which is at least same grade with actuator.

This is not our scope of supply, but if users don’t use suitable component, factory won’t guaranty the performance of ex-proof actuator.

**Electrical wiring**

- Check if electrical specification like as power, wiring & etc are correct or not.
- One sheet of wiring diagram is to be supplied together with actuator.
- Do the wiring as per the given wiring diagram, such as power, control power, internal wiring and ground.
- Make sure to supply electric power to heater for keeping inside of actuator clean and dry.
- Make sure to check wiring to the terminal is strong enough.
- Make sure that one relay operates one actuator only. Can not operate two or more actuators simultaneously.
- Make sure to clean inside of actuator and no foreign material inside.

**Check rotating direction**

- In 3 phase actuator, operator should check the rotating direction of actuator before electrical operation.
- If operating direction is wrong, limit switches doesn’t function and it results damage from jamming or motor's overheating.
- So, put the actuator at 50% open (or Close) position by manual and supply power into the actuator and check its rotating direction.
- If actuator moves t open as per open signal, the direction it is OK, but reverse, need to change the wiring.
- Among 3 of power wires, change 2 wires each other.
- Then check the rotating direction again in order to confirm it again.

**Commissioning**

- Make sure to check the rotating direction of actuator first before operation.
- Check the function of limit and torque switches, direction of indicator, signal LEDs, and space heater.
- Check lever movement is OK (Manual over ride)
- Check the lamps in the control panel.
- After commission, please make sure to tighten the 4 bolts of the top cover and to do proper sealing.

**Other**

**Revere direction actuator**

Generally actuator is set as close for clockwise turning and open for counterclockwise turning. If user want to use reverse direction actuator, please do as follows.

**REA 80**

- Open the cover using L - wrench
- Change wires each other which are connected to terminal no 6 and 7 and do same way for 8 and 9.
- Change the direction of indicator
- Put actuator about 50% open position and check rotating direction is correct.

**REA 150-REA 3000(ON-OFF)**

- Open the cover using L - wrench
- Change wires each other which are connected to terminal no 6 and 7 and do same way for 8 and 9.
- Change the direction of indicator (for HQ200 and 300, change window also)
- Put actuator about 50% open position and check rotating direction is correct.
**REA 150-REA 3000 (Proportional control)**

- Open the cover using L-wrench
- Change wires each other which are connected to terminal no P1 and P3 in the PCU card
- Change wires each other which are connected to terminal no 9 and 10 and do same way for 11 and 12.
- Change the direction of indicator (For REA 2000 and 3000, change the window also)
- Put actuator about 50% open position and just push the auto setting button.
- Supply 4 ~ 20mA and check the operation.

**Potentiometer setting**

- Put actuator full close position and check resistance between P1 (Orange) and P3 (Grey), it should be around 10000ohm.
- Put the resistance between P1 (Orange) and P2 (Purple) of potentiometer around 80~120 Ohm.
- Engage potentiometer gear with pointer shaft gear and tighten the bolt.
- Put spring between potentiometer and pointer shaft and fix both.
- If user wants to use revere direction actuator, change the wires of P1 (Orange) and P3 (Grey) of PIU each other.

**Jamming**

- In case that actuator moves wrong direction and moves over the travel limit, internal worm gear contacts the stopper bolt and engaged each other. This is we call, jamming and can not move actuator at all.
- How to solve
  
  a. Off the power
  b. If jamming is happened during close, take close stopper bolt to come out by about 2~3 threads
  c. Pull over the lever and put it manual position.
  d. Turn hand wheel to counterclockwise until 50% open position.
  e. Check rotating direction again.
  f. If everything is O.K, put stopper bolt original position.
  g. If jamming is happened during open, procedure is same with close, but turn hand wheel to clockwise by manual.
Special tools for setting
- L-Wrench 1 set (Metric)
- Screw drivers - , +
- Spanner set (Metric), Monkey spanner 200mm, 300mm 1 each
- Wire stripper, Long nose, Light
- Multi Meter (AC, DC Volt, Resistance)
- DC signal generator (0 ~ 4mA DC) : PCU option
- MA DC Meter (0 ~ 25mA DC) : PCU and CPT

PRECAUTION BEFORE USING ACTUATOR

A. Selection of valve and actuator: Review all specification of valve and actuator carefully before making selection and reserve about 30% torque of actuator for safety purpose. If required torque is 90Kg- m, recommended actuator torque is about 117Kg- m.

B. Option: Please consult with factory before making selection, if possible.

C. Before necessary setting such as limit switch, please don’t operate actuator either fully open or fully close.

D. After electrical wiring, make sure to secure the sealing of cable entries.

E. Before operating actuator, please review this manual carefully and follow the instruction without fail. Please be careful at temperature, humidity, vibration, voltage drop.

F. Storage: Keep actuator dry, clean and cool.

G. Trouble: Please refer to following trouble shooting but please don’t dismantle the actuator without consulting with factory.

H. If repair or maintenance is required, please check the model, electrical condition, serial Number and current situation to inform factory.
## Trouble shooting

**110/220VAC 1Ph, 380/440VAC 3Ph standard actuator**

<table>
<thead>
<tr>
<th>Trouble</th>
<th>Cause</th>
<th>Counter plan</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Actuator doesn't work at all</strong></td>
<td>Check if power is on</td>
<td>Power on</td>
</tr>
<tr>
<td></td>
<td>Check if voltage is too low</td>
<td>Check power</td>
</tr>
<tr>
<td></td>
<td>motor and supplied power is different</td>
<td>Check motor power and supplied power</td>
</tr>
<tr>
<td></td>
<td>wiring is not correct and tight or loosen</td>
<td>Do wiring again tightly</td>
</tr>
<tr>
<td></td>
<td>coil of motor is damaged</td>
<td>Change the motor</td>
</tr>
<tr>
<td></td>
<td>thermostat of motor trips</td>
<td>Change thermostat</td>
</tr>
<tr>
<td></td>
<td>capacitor is damaged</td>
<td>Change the capacitor</td>
</tr>
<tr>
<td></td>
<td>setting of limit and torque switch is not correct</td>
<td>Do setting switches again</td>
</tr>
<tr>
<td></td>
<td>jamming happens</td>
<td>Check rotating direction per instruction</td>
</tr>
<tr>
<td><strong>Torque switch open</strong></td>
<td>Actuator is undersized</td>
<td>Select again as per real required torque</td>
</tr>
<tr>
<td></td>
<td>Foreign material between valve seat and disc</td>
<td>Remove foreign material</td>
</tr>
<tr>
<td></td>
<td>Stopper bolt is set prior to limit switch</td>
<td>Reset the stopper bolt</td>
</tr>
<tr>
<td><strong>Switching to manual is not possible</strong></td>
<td>Lever is not fully pulled over</td>
<td>Fully pull over the lever</td>
</tr>
<tr>
<td></td>
<td>Lever is not pulled over because of Jamming</td>
<td>Disengage the jamming</td>
</tr>
<tr>
<td></td>
<td>Clutch of lever and handle is engaged each other</td>
<td>Turning handle slowly, pull over lever</td>
</tr>
<tr>
<td><strong>Abnormal signal indicator</strong></td>
<td>Damage of Signal LED</td>
<td>Change the signal LED</td>
</tr>
<tr>
<td></td>
<td>Damage of micro switches</td>
<td>Change the micro switches</td>
</tr>
<tr>
<td></td>
<td>Setting of limit switch is wrong</td>
<td>Do setting switch again</td>
</tr>
<tr>
<td></td>
<td>Stopper bolt is set prior to limit switch</td>
<td>Do setting stopper bolt again</td>
</tr>
<tr>
<td><strong>Remote operation is not possible</strong></td>
<td>Wiring is not correct</td>
<td>Do wiring again</td>
</tr>
<tr>
<td></td>
<td>Switch is not correct</td>
<td>Put the switch at remote position</td>
</tr>
</tbody>
</table>

### PCU option

<table>
<thead>
<tr>
<th>Trouble</th>
<th>Cause</th>
<th>Counter plan</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>PCU doesn't work</strong></td>
<td>Input signal is not applied</td>
<td>Check input signal</td>
</tr>
<tr>
<td></td>
<td>PIU signal is failed</td>
<td>Check the resistance of potentiometer and change it if resistance is not correct</td>
</tr>
<tr>
<td></td>
<td>PCU card is damaged</td>
<td>Change the PCU card</td>
</tr>
<tr>
<td><strong>Output signal is not detected</strong></td>
<td>PIU signal is failed</td>
<td>Check the resistance of potentiometer and change if resistance is not correct</td>
</tr>
<tr>
<td></td>
<td>PCU card is damaged</td>
<td>Change PCU card</td>
</tr>
</tbody>
</table>
## CPT Option

<table>
<thead>
<tr>
<th>Trouble</th>
<th>Cause</th>
<th>Counter plan</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output signal</td>
<td>PIU signal is failed</td>
<td>Check the resistance of potentiometer and change if resistance is not correct</td>
</tr>
<tr>
<td>is not detected</td>
<td>PCU card is damaged</td>
<td>Change PCU card</td>
</tr>
</tbody>
</table>

## Maintenance

### Lubrication

Lubrication is already done by factory and generally no need to refill it again. But in the places such as very dry condition below R.H 15% or high temperature higher than 30 °C, it is required to do lubrication once two year through Grease Nipple.

### Regular operation

Electrical power always should be supplied to actuator and it is recommended to operate actuator once a week.

### Maintenance

In order to use actuator for long time, regular maintenance once a year is required. Please check operating condition, corrosion, painting & etc.

### Others

Should you have any further queries, please contact us through Phone, fax and E-mail without hesitation.